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GOES-16 ABI Aerosol Detection Product

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IMSG



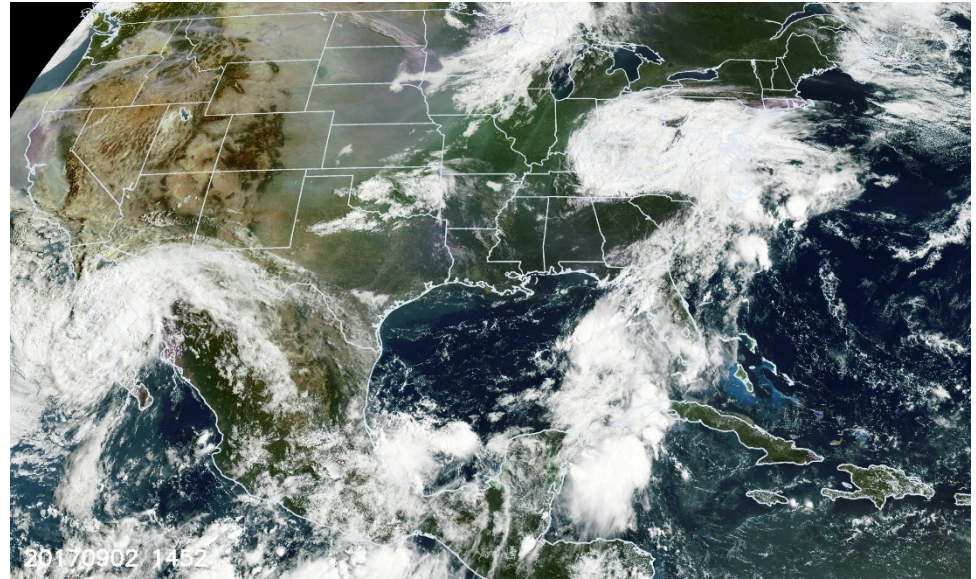
GOES-16 ABI Aerosol Detection Product

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- Identify the presence of aerosol in the atmosphere and classify it as dust or smoke.
 - ▣ Required accuracy: 80% for dust; 70% for smoke

	GOES-R ABI
Spatial	2 km
Temporal	15 min
Coverage	Regional

- ▣ Qualitative imagery product
- Useful applications: operational air quality forecasting; aerosol data assimilation in numerical models



**GOES-16 ABI Synthetic
RedGreenBlue Image**



GOES-16 ABI Smoke Detection over Land

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$$R_{2.25 \mu m} \times 100 < 20$$

$$R_{0.64 \mu m} \times 100 > (6 + R_{2.25 \mu m} \times 100)$$

$$R_1 \geq 0.85$$

$$R_2 \geq 1.0$$

$$\sigma_{R_{0.64 \mu m}} \leq 0.04$$

$$R_1 = \frac{R_{0.47 \mu m}}{R_{0.64 \mu m}}, \quad R_2 = \frac{R_{0.86 \mu m}}{R_{0.64 \mu m}}$$

- Smoke is transparent at $2.25 \mu m$ and bright at $0.64 \mu m$
- Reflectance ratios allow smoke/clear sky discrimination
- Spatial variability test minimizes mis-identification of cloud as smoke



GOES-16 ABI Dust Detection over Land

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Thin dust detection

$$BT_{11\mu\text{m}} - BT_{12\mu\text{m}} \leq -0.2K$$

$$BT_{3.9\mu\text{m}} - BT_{11\mu\text{m}} \geq 15K$$

$$R_{1.38\mu\text{m}} < 0.035$$

if $BT_{3.9\mu\text{m}} - BT_{11\mu\text{m}} \geq 20K$ then dust

if $(MNDVI < 0.08) \& (Rat_2 > 0.005)$ then dust

$$NDVI = \frac{R_{0.86\mu\text{m}} - R_{0.64\mu\text{m}}}{R_{0.86\mu\text{m}} + R_{0.64\mu\text{m}}} \quad MNDVI = \frac{NDVI^2}{R_{0.64\mu\text{m}}^2}$$
$$Rat_1 = \frac{R_{0.64\mu\text{m}} - R_{0.47\mu\text{m}}}{R_{0.64\mu\text{m}} + R_{0.47\mu\text{m}}} \quad Rat_2 = \frac{Rat_1^2}{R_{0.47\mu\text{m}}^2}$$

Thick Dust detection

$$BT_{11\mu\text{m}} - BT_{12\mu\text{m}} \leq -0.5K$$

$$BT_{3.9\mu\text{m}} - BT_{11\mu\text{m}} \geq 25K$$

$$R_{1.38\mu\text{m}} < 0.055$$

if $MNDVI < 0.2$ then dust

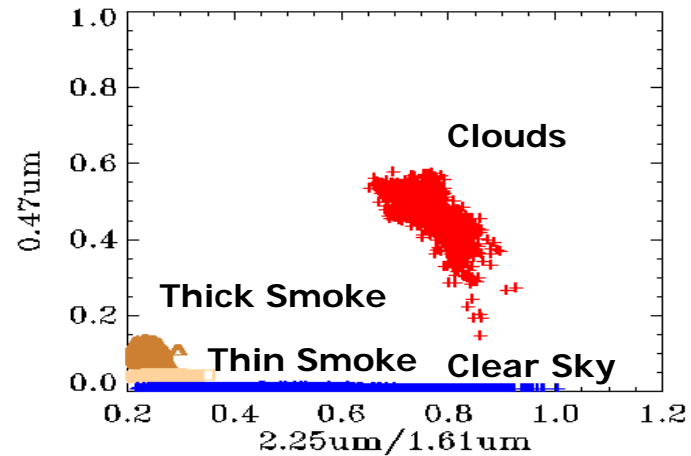
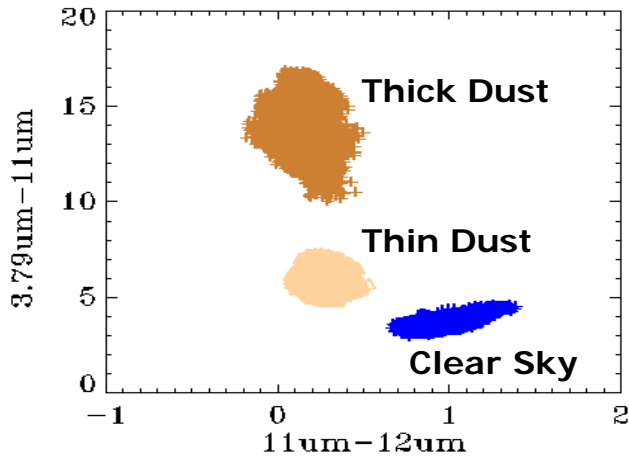
- Dust absorbs more at 11 μm than at 12 μm
- Spatial variability test minimizes mis-identification of smoke as cloud
- Cirrus test



Aerosol Detection Spectral Tests

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For illustration purpose, scenes with dust, smoke, clouds, and clear sky over Ocean were manually chosen



Algorithm takes advantage of spectrally varying absorption and scattering of dust, smoke, clouds, and surface

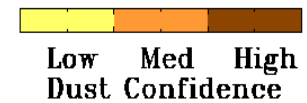
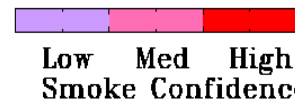
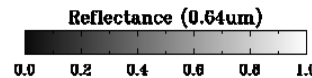
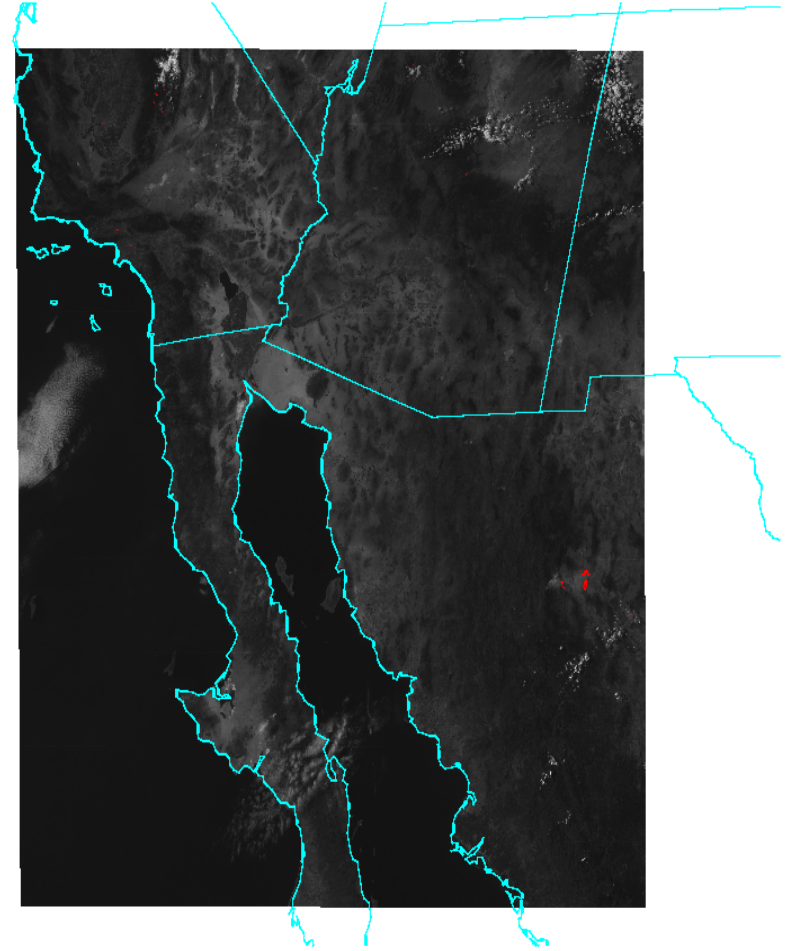


GOES-16 ABI Aerosol Detection Product

2017-121 UTC:23:12 ADP Smoke/Dust Confidence Flag

6

Mesoscale Mode



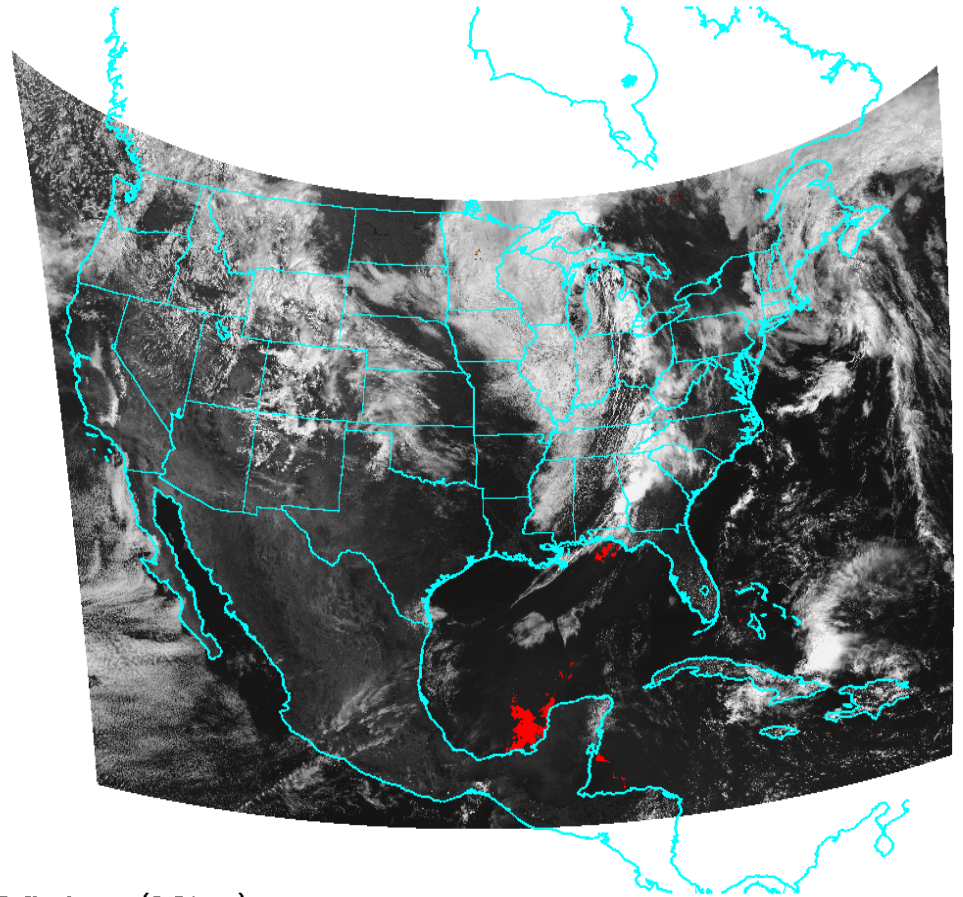


GOES-16 ABI Aerosol Detection Product

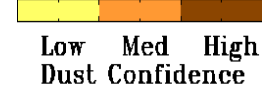
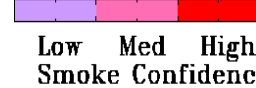
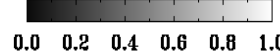
7

2017-117 UTC:16:27 ADP Smoke/Dust Confidence Flag

CONUS Mode



Reflectance (0.64 μ m)



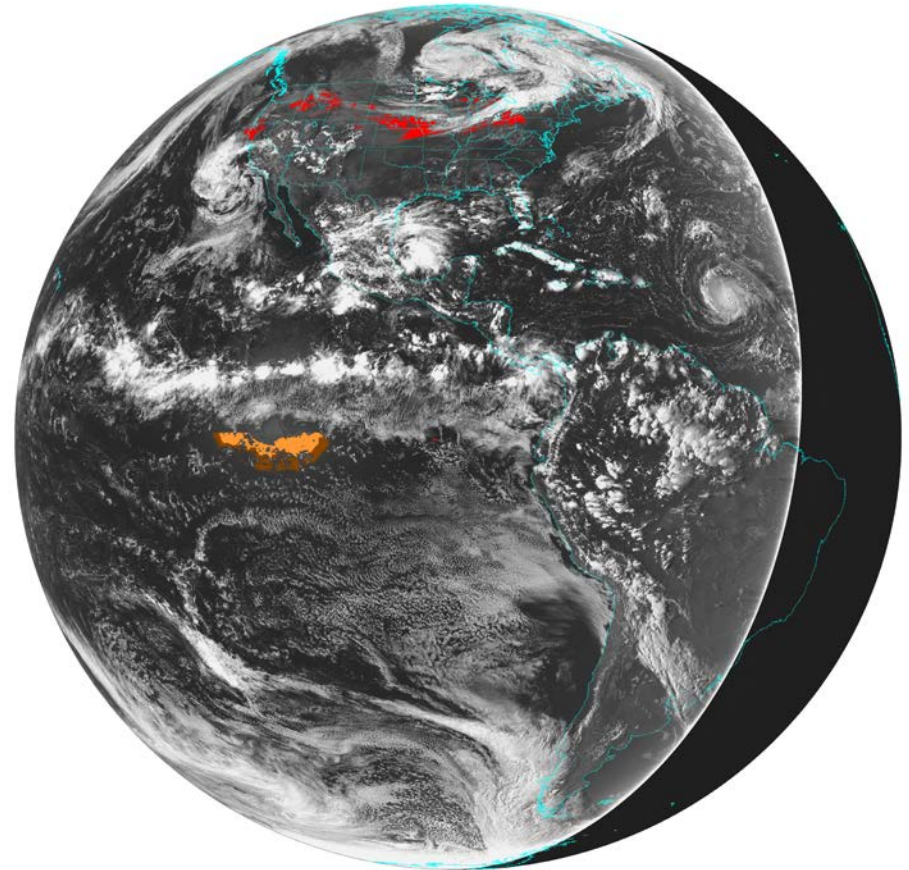


GOES-16 ABI Aerosol Detection Product

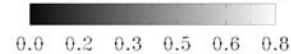
8

2017-247 UTC:21:00 ADP Smoke/Dust Confidence Flag

Full Disk Mode



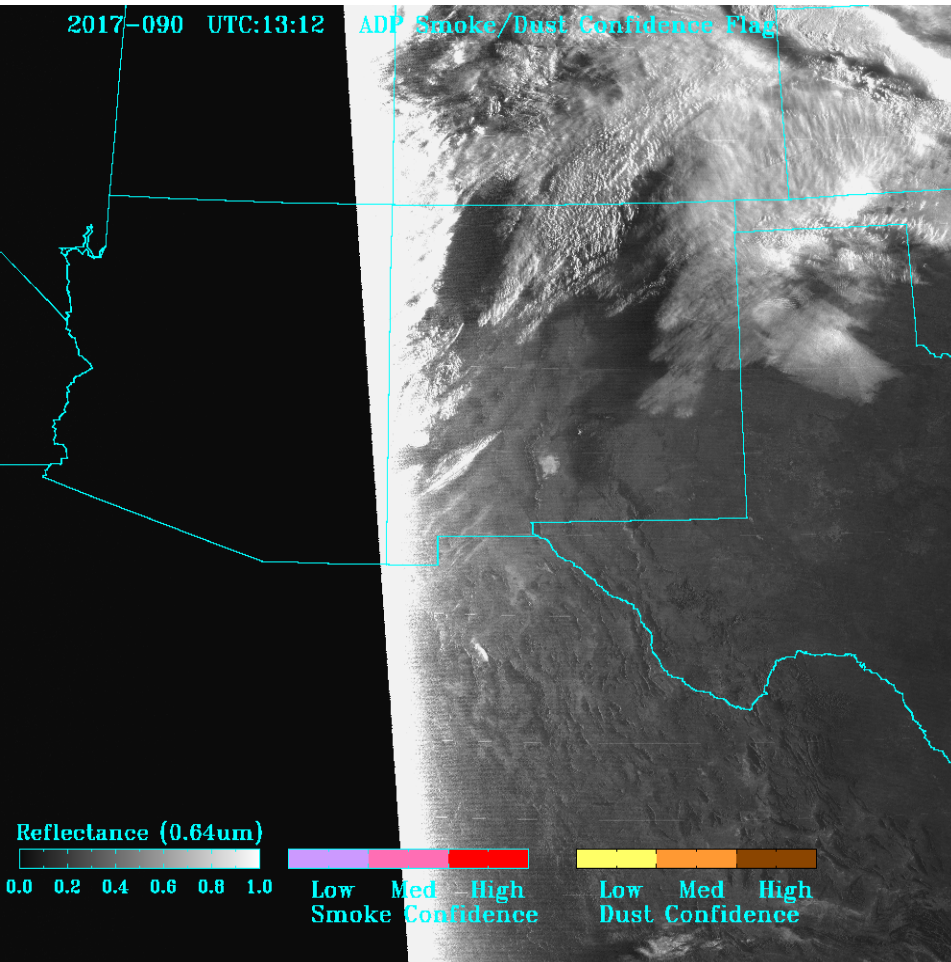
Reflectance (0.64 μ m)



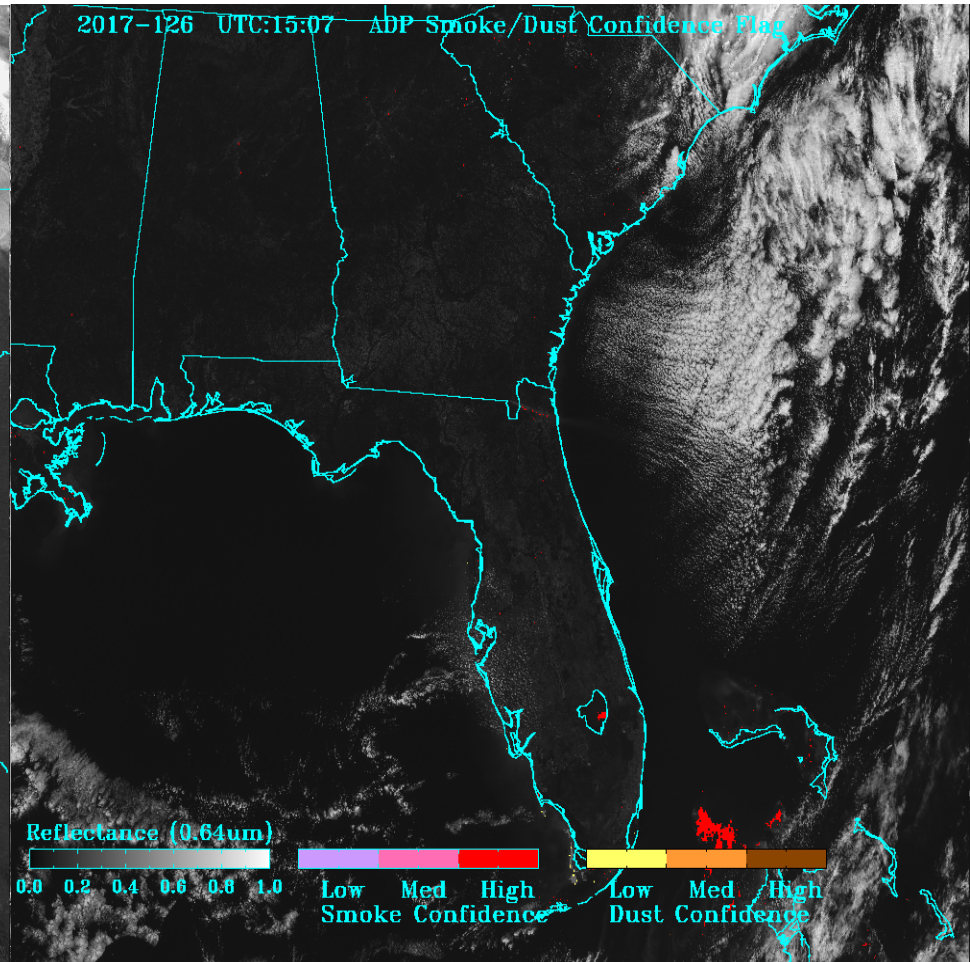


GOES-16 ABI Aerosol Detection Product

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March 31, 2017



May 6, 2017



GOES-16 ABI Aerosol Detection Product Validation

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- Primary validation is to compare to other correlative measurements
 - CALIPSO
 - Space-borne LIDAR which provides aerosol classification
 - AERONET
 - Ground based aerosol instrument that provides particle size information which is used to classify aerosol observations into dust/smoke/haze
 - Hazard Mapping System
 - Human analysis of smoke plume

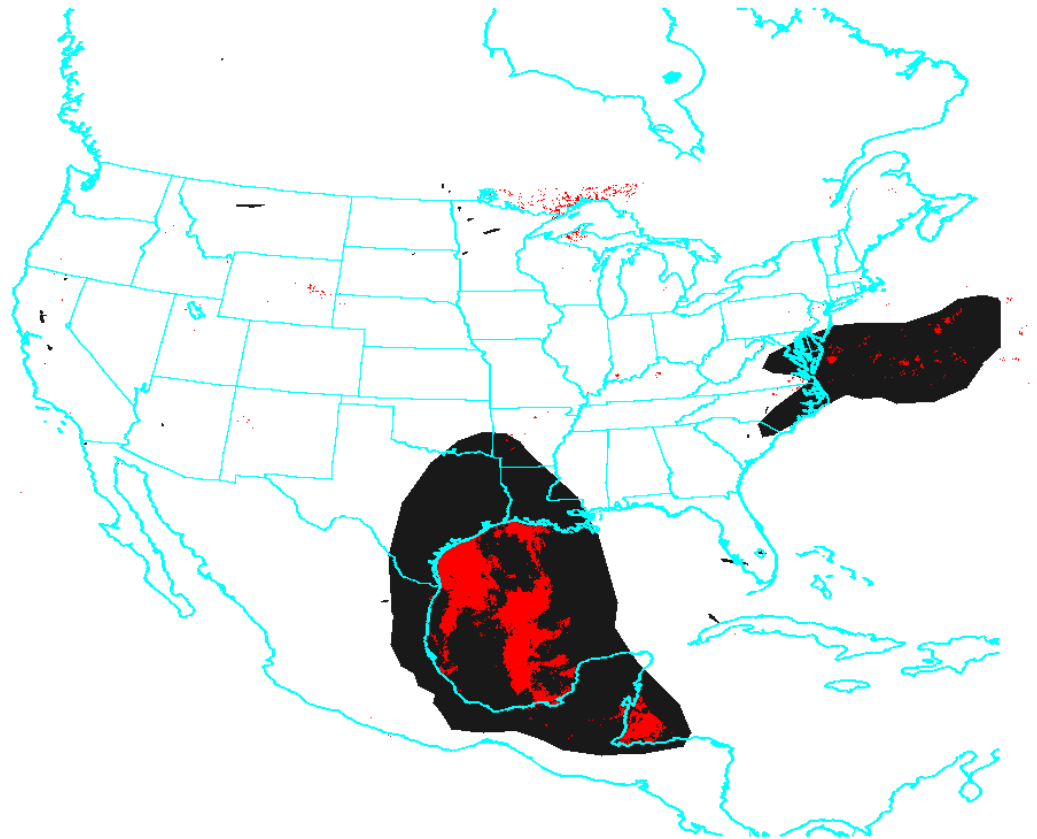
Three metrics are computed: Accuracy, Probability of Correct Detection, Probability of False Detection



GOES-16 ABI ADP vs. HMS

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2017-119 ADP Smoke/Dust Confidence Flag



Low Med High
Smoke Confidence

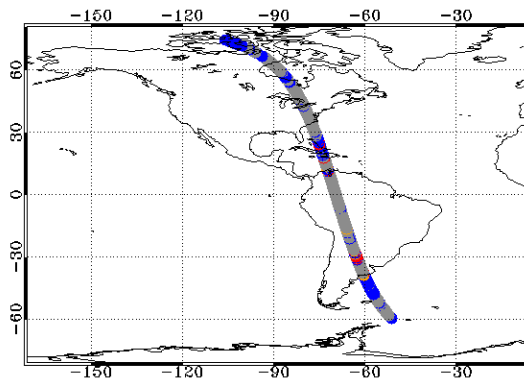
Low Med High
Dust Confidence



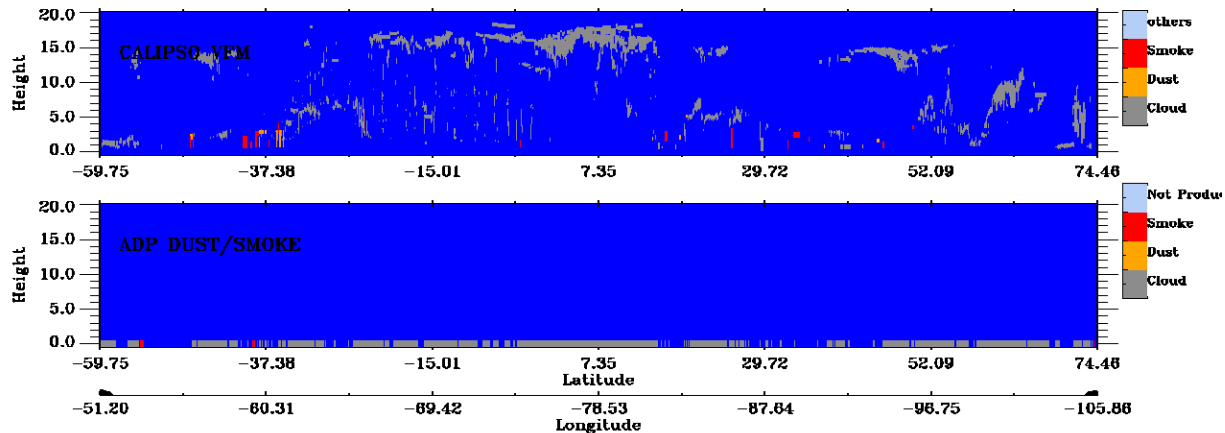
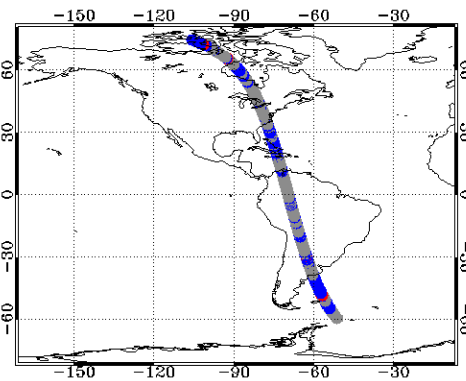
GOES-16 ABI ADP vs. CALIPSO

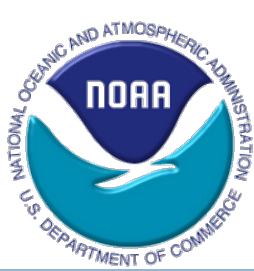
12

CALIPSO VFM



ADP DUST/SMOKE

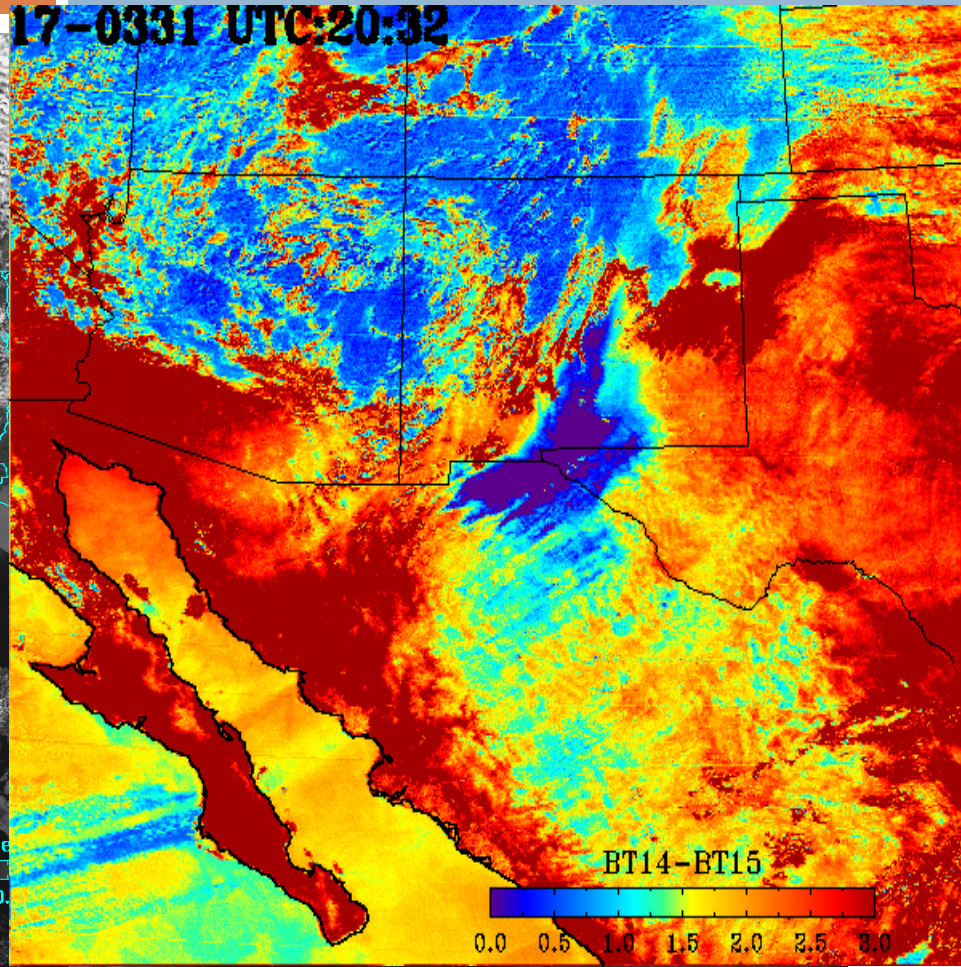




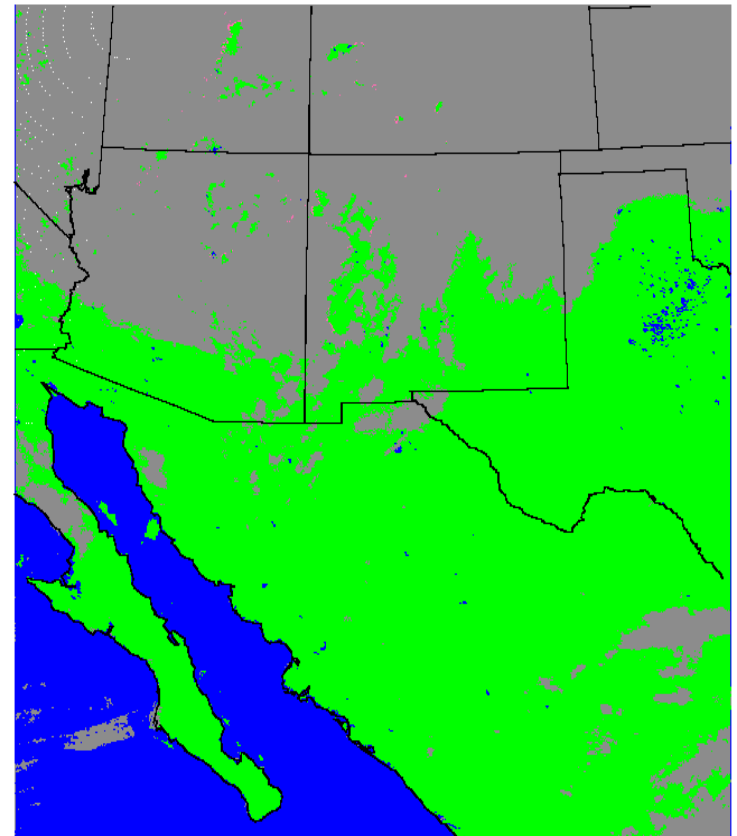
Data Artifacts

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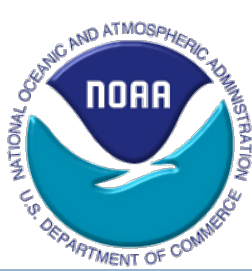
17-0331 UTC:20:32



2017-090 UTC:20:32 ADP Quality Infor Flags



No Data Night Land Water ABI Snow/ice IMS source Internal Clds



Validation Summary

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- Validation against RGB, DUST RGB and Natural color imagery shows GOES-16 Aerosol Detection Product (ADP) product is capturing the events.

- Validation metrics improve after calibration update
 - ▣ GOES-16 vs. HMS shows improvement
 - ▣ Matchups with CALIPSO, AERONET, and CATS need to be stratified (before/after calibration update) to analyze improvements in performance.
Not enough matchups to do this analysis as of this review

- Aerosol team is planning to tune ADP threshold tests to improve product performance
 - ▣ Angle dependent thresholds
 - ▣ Improved cloud mask
 - ▣ ABI specific thresholds (*current thresholds are based on MODIS*)



Beta Maturity

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- GOES-16 at a checkout position of 89°W. Will move to East (75°W) position later this year;
- Algorithm relies on various spectral and spatial variability tests
 - ▣ Based on MODIS. Need updates
 - ▣ No prior experience with similar capabilities from a geostationary orbit
 - Need to look at actual ABI data, understand the time of the day retrieval issues, and tune thresholds we put in for various tests



Beta Maturity → Provisional

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Level 1b data must be provisional and calibration must be up to date and accurate

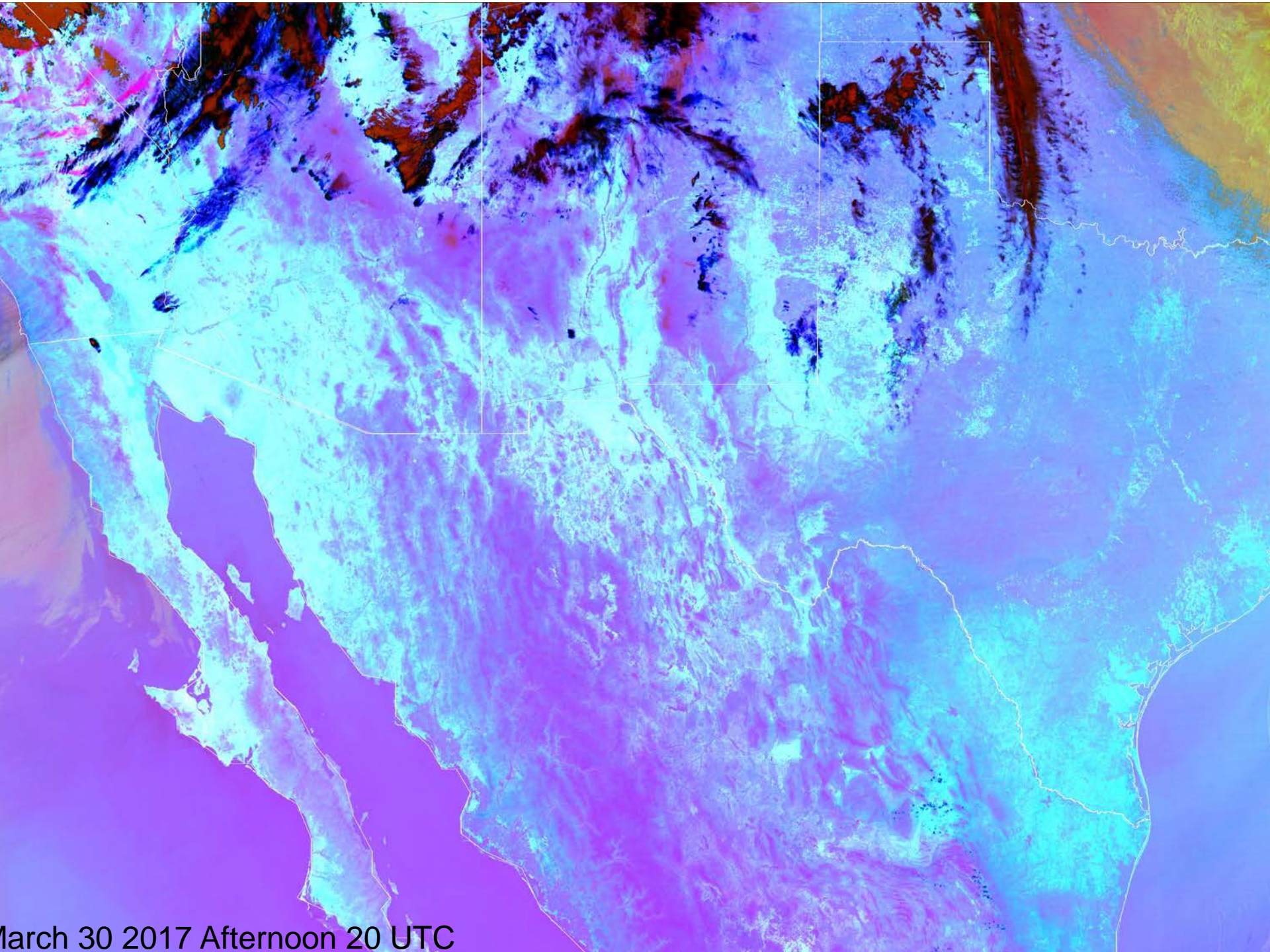
Cloud mask, snow/ice mask must be provisional

A local archive of collocated L1, L2, and PQI over AERONET sites will be analyzed to revise:

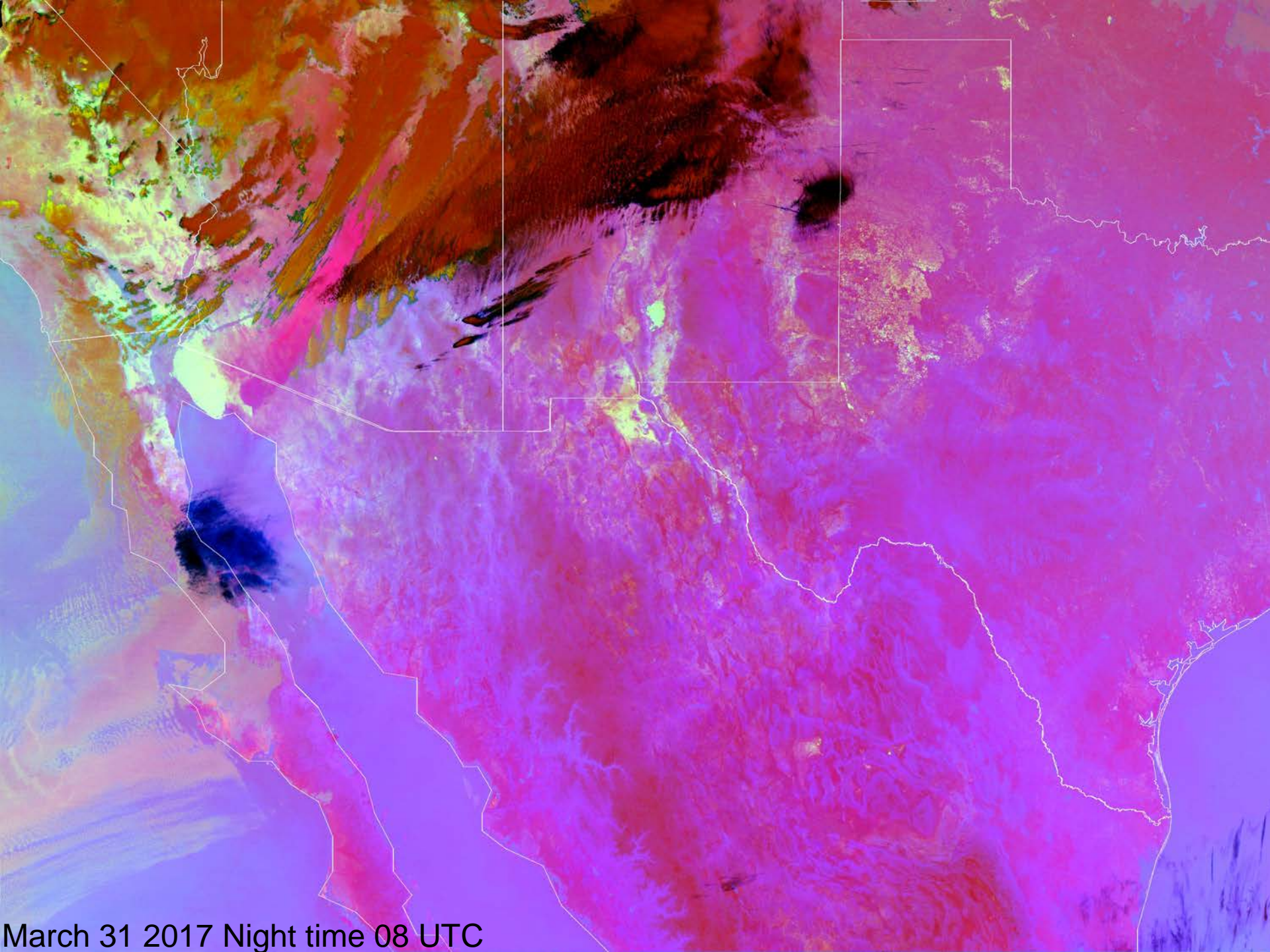
- Thresholds used for various spectral tests. *Baseline algorithm consists of values based on MODIS*
- Develop and apply view geometry dependent thresholds for various tests to improve detection and minimize false detections
- Understand product performance as a function of
 - Over land vs. ocean
 - Time of the day
 - Land surface type
- Initial feedback from operational forecasters



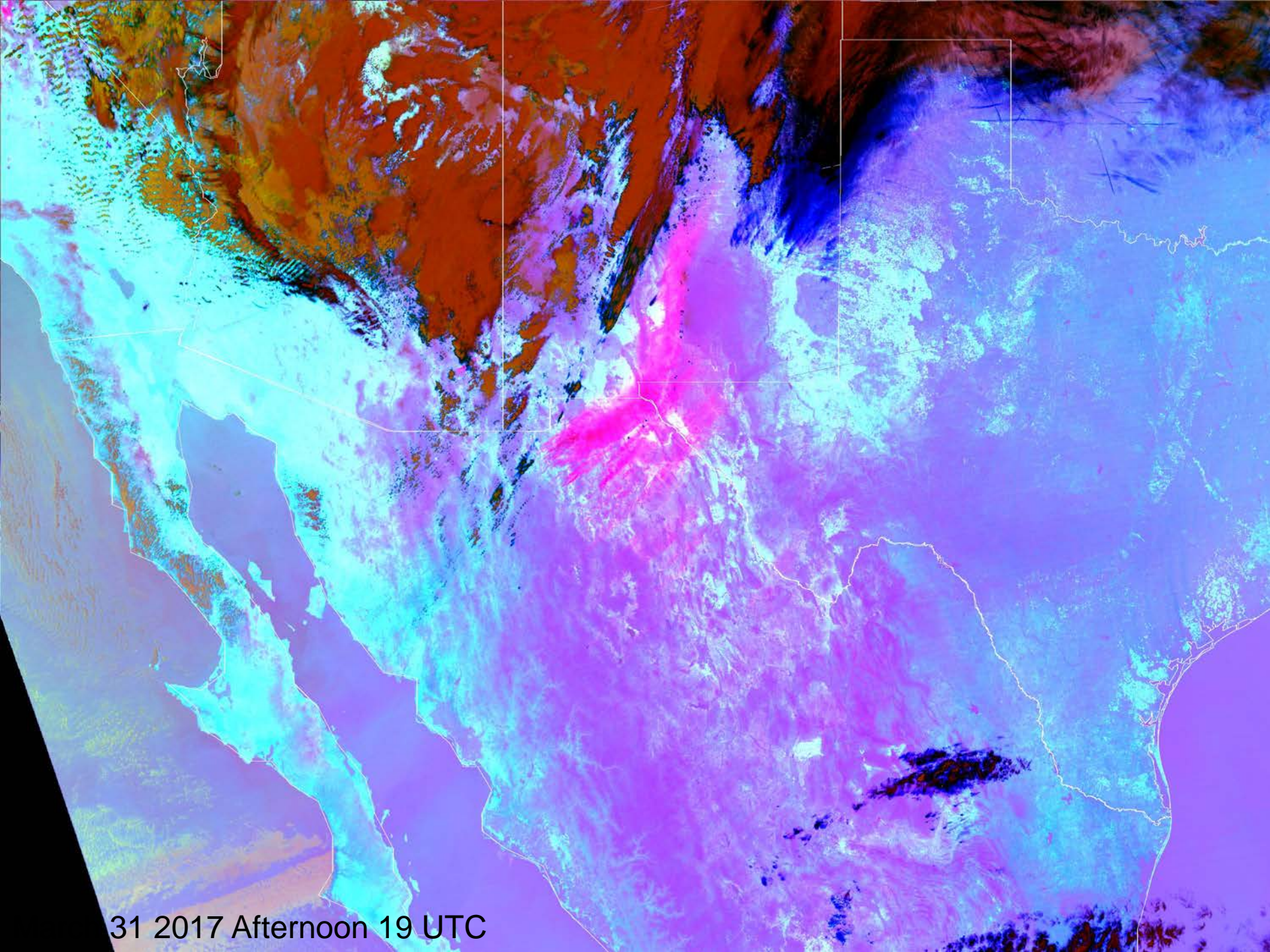
Geo vs. Leo (Dust Case)



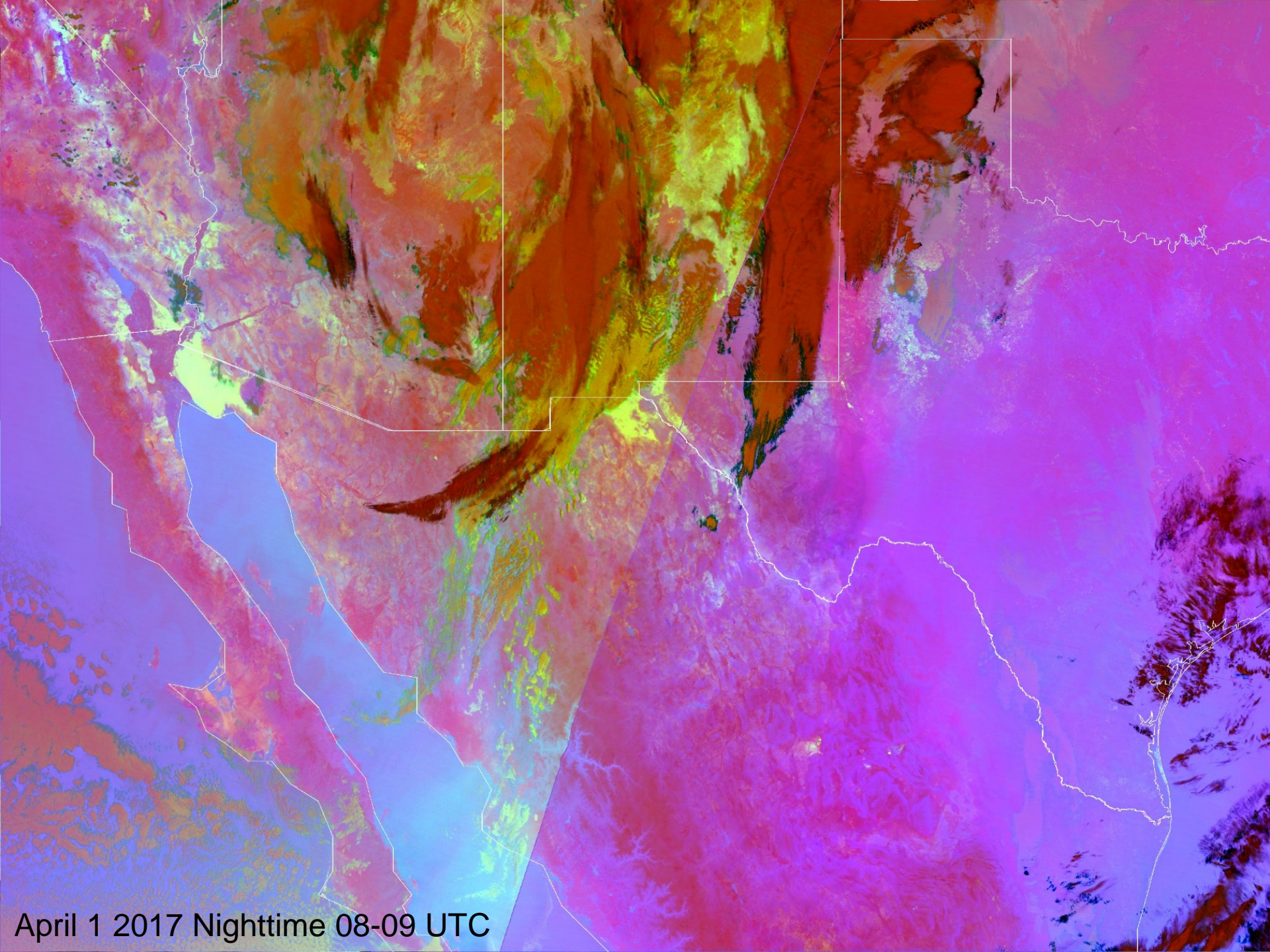
March 30 2017 Afternoon 20 UTC



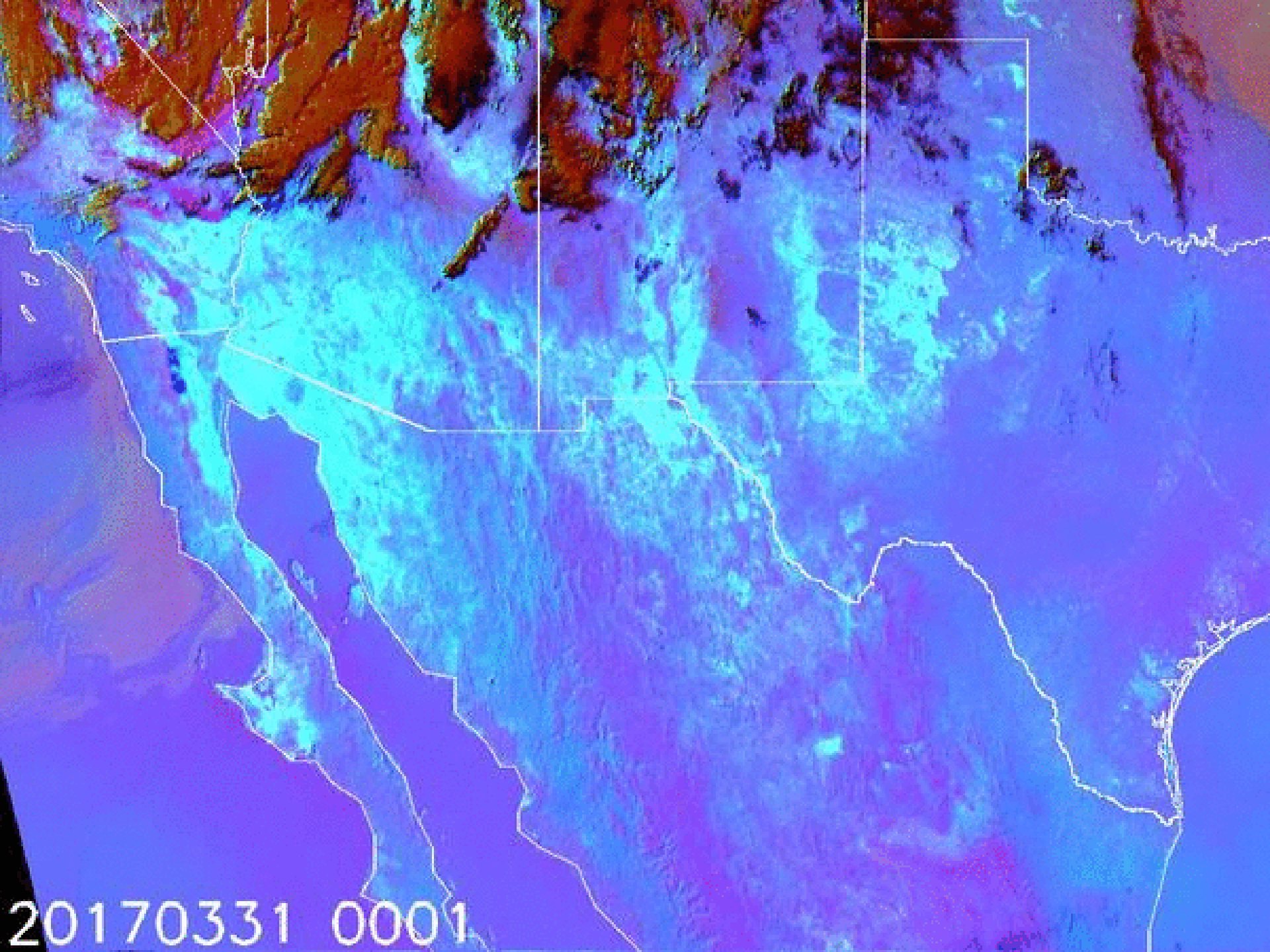
March 31 2017 Night time 08 UTC



31 2017 Afternoon 19 UTC



April 1 2017 Nighttime 08-09 UTC



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